

Machine Vision Iasonas Oikonomidis Alexandros Makris Kostas Papoutsakis





Course Info

Class Schedule

- .Friday 4-6: Theory
- •Friday 6-8: Lab

Grading

- Participation 20%
- •Python programming Assignments 80%.

.Prerequisites

- .Linear algebra
- Probabilities
- .Programming

Course Info

Site: https://eclass.hmu.gr/courses/TM152/

(pwd:cv2019)

- Textbooks:
 - Forsyth & Ponce, Computer Vision: A Modern Approach
 - Szeliski, Computer Vision: Algorithms and Applications.
 - Hartley, Zisserman, Multiple View Geometry in Computer Vision.



The goal of Computer Vision

Make computers understand images.

(e.g. photos, videos, medical images)





What Kind of information?



Information

Information

Semantic Information: Scene and Context



Semantic Information: Object Recognition





Connections to other disciplines



Computer Vision vs Graphics

$$I = f(C_{amera}, L_{ight}, M_{aterial}, S_{tructure})$$

Computer Graphics: Knowing C, L, M, S, construct I. Computer Vision: Knowing I, extract C, L, M, S.

Computer Vision Applications

Cartography



Intelligent Vehicles



Robotics



Security



Medical



Multimedia Databases



Computer Vision Examples

Optical Character Recognition (OCR)

- Convert scanned documents to text.
- . License plate readers.
- . Automatic check processing.



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Biometrics

Fingerprint recognition Face recognition





Face Detection



Digital Cameras

On-line services, social networks.



Smile Detection





Intelligent Vehicles









Sports







3D Body Tracking (Kinect)









3D Hand Tracking







https://youtu.be/3yvaFuX09xY?t=21

Mobile Robots









Challenges: viewpoint variation



Challenges: Illumination



Challenges: Scale



Challenges: Deformation



Challenges: Appearance variation.









Challenges: Occlusion



Challenges: Background Clutter



Challenges: Ambiguity

Many different 3D scenes could have given rise to a particular 2D picture.



Course Overview

- Image Formation
- Linear Filters
- Edge & Corner
 detection
- Feature Extraction
- Grouping and fittingHough Transform

- Alignment
- Stereo Vision
- Segmentation
- Image/Object Recognition
- Video Recognition
- Motion & Tracking
- Deep Learning for Computer Vision

Image Formation



Filtering



Feature Extraction



Corner and blob detection

Grouping and Model Fitting





Fitting: Least squares, Hough transform, RANSAC.

Stereo Vision

- •Adds depth to the image.
- •<u>Stereo Occupancy</u> <u>Grids</u>



Motion and Optical Flow



Tracking

https://youtu.be/Z9X3IhHytrQ?t=78



Object Segmentation vs Detection

Pixel-level labels Category only Bounding box labels Category + instance



Object Recognition





Image/Video Recognition

(assume given set of discrete labels) {dog, cat, truck, plane, ...}



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Deep Learning



